

A statistical tour of physics-informed machine learning

Focus on physics-informed neural networks (PINNs)

* for simplicity.

Setting:

$\Omega \subset \mathbb{R}^{d_{\text{in}}}$ bounded Lipschitz domain

ex: bounded convex domains

$C^k(\Omega, \mathbb{R}^{d_{\text{out}}})$ space of functions from Ω to $\mathbb{R}^{d_{\text{out}}}$
k-time continuously differentiable.

$$C^\infty(\Omega, \mathbb{R}^{d_{\text{out}}}) = \bigcap_{k \geq 0} C^k(\Omega, \mathbb{R}^{d_{\text{out}}})$$

Hölder norm $\|f\|_{C^k(\Omega)} = \max_{|k| \leq k} \|\partial^k f\|_{\infty, \Omega}$

Hybrid modelling

- Goal: to estimate an unknown regression function f^* such that $f^*: \Omega \rightarrow \mathbb{R}^{d_{\text{out}}}$ and

$$y = f^*(x) + \varepsilon$$

random noise $E[\varepsilon|x] = 0$.

In traditional supervised learning, to do so we use
training samples (X_i, Y_i) $i=1..n$ independent copies of
 (X, Y) distributed as $\otimes$

- Additional information: physical modeling / prior knowledge

$$\mathcal{D}(f^*, \cdot) \simeq 0 \quad \text{on } \Omega.$$

known differential equation

- Additional information: Initial / Boundary condition on $E \subseteq \partial\Omega$
partial knowledge allowed.

ex: when $E = \partial\Omega$, Dirichlet boundary condition.

- To estimate f^* , we have 3 different data sets

① the "traditional" training samples (unknown distribution)

$$(X_1, Y_1) \dots (X_n, Y_n)$$

② Collocation points: a collection of iid points (uniformly distributed on Ω)

$$X_1^{(n)}, \dots, X_n^{(n)}$$

These points can be seen as a naive discretization of Ω .

③ Condition points: a collection of iid points $N \mu_E$ on E

$$X_1^{(e)}, \dots, X_n^{(e)}$$

(known distribution μ_E on E)

- physics-informed empirical risk

$$R_{n, n_d, n_e}(f) = \underbrace{\frac{1}{n} \sum_{i=1}^n \|f(x_i) - y_i\|_2^2}_{\text{Data-fidelity term}} + \underbrace{\frac{\lambda_d}{n_d} \sum_{i=1}^n \|\mathcal{D}(f, x_i^{(d)})\|_2^2}_{\text{PDE term}} + \underbrace{\frac{\lambda_e}{n_e} \sum_{i=1}^n \|f(x_i^{(e)}) - h(x_i^{(e)})\|_2^2}_{\text{Initial/boundary conditions}}$$

can be an absolute value for simplicity

I may drop the initial/boundary conditions for the sake of presentation.

- When this physics-informed risk is minimized over a class of neural networks, we obtain the so-called **physics-informed neural networks** (PINNs)

To do so, consider the class of **fully-connected** feed forward NN with H hidden layers of width $(L_1, L_2, \dots, L_H) = (D, D, \dots, D)$
 an input layer of width $L_0 = d_{in} = d$ ($\Omega \subset \mathbb{R}^{d_{in}=d}$)
 an output layer of width $L_{H+1} = d_{out} = 1$ ($y \in \mathbb{R}^{d_{out}=1}$)
 activation function $\tanh$

Overall,

$$f_0 = A_{\text{out}} \circ (\tanh \circ A_H) \circ \dots \circ (\tanh \circ A_1)$$

↑ applied component-wise

with $A_k : \mathbb{R}^{L_{k-1}} \rightarrow \mathbb{R}^{L_k}$

weight matrix $W_k \in \mathbb{R}^{L_{k-1} \times L_k}$

$$x \mapsto W_k x + b_k$$

bias

$$b_k \in \mathbb{R}^{L_k}$$

The parameters of the neural network - to be learned - are encoded

by $\Theta = (W_1, b_1, \dots, W_{H+1}, b_{H+1}) \in \bigoplus_{H+1} D$

$$\mathbb{R}^{\sum_{k=1}^H (L_{k-1} \times L_k + L_k)}$$

Notation: $NN_H(D) \equiv$ neural networks

of H hidden layers
of width D .

H hidden layers
of width D

Approximation results

Ideally, the NN set $NN_H(D)$ should be chosen large enough to approximate both the solution of the PDE and its derivatives.

Prop: [Density of NN in Hölder space, De Ryck et al (2021), Deumeche et al (2023)]

For $H \geq 2$, NN_H is dense in the space $(C^\infty(\bar{\Omega}, \mathbb{R}^{\text{data}}), \|\cdot\|_{C^K(\Omega)})$

i.e. for any function $u \in C^\infty(\bar{\Omega}, \mathbb{R}^{\text{data}})$, $\exists (u_k)_{k \in \mathbb{N}} \in NN_H$

such that $\lim_{k \rightarrow \infty} \|u_k - u\|_{C^K(\Omega)} = 0$

for any K

Theorem [Györfi, 2017]

For every $\varepsilon > 0$, for every $f \in \mathcal{B}^k([0,1]^d)$, there exists a
tanh neural network $\hat{f}$ with $O(\varepsilon^{-d/k})$ neurons such that
 $\|f - \hat{f}\|_\infty < \varepsilon$.

NN structure allows for constructive proof

Key properties

- sum or composition of NN is a NN
- For smooth activation fct σ with $\sigma'(0) \neq 0$, and $|x| \leq B$
 $\forall h > 0 \quad \alpha = \frac{\sigma(xh) - \sigma(-xh)}{2h\sigma'(0)} + O(B^3 h^2)$

Approximation of identity with 2 neurons -

Theorem [De Ryck, Lanthaler, Mishra, 2021]

For every $N \in \mathbb{N}$ and every $f \in \mathcal{B}^k([0,1]^d)$, $\exists$ a tanh
neural network $\hat{f}$ with 2 hidden layers of width N^d such that
for every $0 \leq k \leq s$,

$$\|f - \hat{f}\|_{C^k} \leq C \left(\ln(cN) \right)^k N^{-s+k}$$

$\uparrow$ $\uparrow$
 $\ll N$ $\ll N$

Remark 1

also holds for Sobolev norms -

Remark 2

How to translate this in terms of PDE residuals

Example of the heat equation

$$\mathcal{R}(f, x) = \partial_t f - \partial_{xx}^2 f$$

when $f^* \in C^2([0, T] \times [0, 1])$

$$\textcircled{1} \quad \|\partial_t \hat{f} - \partial_{xx}^2 \hat{f}\|_{L^2(\Omega)} \leq \sqrt{|\Omega|} \quad \|\partial_t \hat{f} - \partial_{xx}^2 \hat{f}\|_{\infty/C^0}$$

$$\textcircled{2} \quad \|\partial_t \hat{f} - \partial_{xx}^2 \hat{f}\|_{C^0} = \|\underbrace{\partial_t \hat{f} - \partial_t f^* + \partial_{xx}^2 f^*}_{=0} - \partial_{xx}^2 \hat{f}\|_{C^0}$$

$$\leq \|\partial_t \hat{f} - \partial_t f^*\|_{C^0} + \|\partial_{xx}^2 \hat{f} - \partial_{xx}^2 f^*\|_{C^0}$$

$$\leq \|\hat{f} - f^*\|_{C^1} + \|\hat{f} - f^*\|_{C^2}$$

$$\leq 2 \|\hat{f} - f^*\|_{C^2}$$

Therefore, there is a NN with 2 hidden layers and N^2 neurons s.t.

$$\|\partial_t \hat{f} - \partial_{xx}^2 \hat{f}\|_{L^2} \leq 2\sqrt{|\Omega|} \|\hat{f} - f^*\|_{C^2} \leq C (\ln(cN))^2 N^{-8+2}.$$

Remark 3 : in practice, the PINNs are of size.

NN₄(50) Krishnapriyan et al. "Characterizing failure modes in PINNs"

NN₅(100) Xu et al. "How NN extrapolate: from FFNN to GNN".

NN₁₀(100) Arzani et al. "Blood flow".

Back to learning

- In traditional supervised learning, we have the statistical model

$$Y = f^*(X) + \text{noise} \quad (\Delta)$$

such that $E[\text{noise} | X] = 0$.

target function

- Introduce the quadratic risk $Risk(f) = E[(Y - f(X))^2]$

- This risk is minimal for $f : x \mapsto E[Y | X=x]$.
 $f = f^*$. (Bayes predictor)

- To estimate f^* , we use n training samples (X_i, Y_i) $i=1 \dots n$ iid as (X, Y) distributed as (Δ) , and construct an estimator $\hat{f}_n$.

- The first statistical requirement is to hope for risk consistency

$$\lim_{n \rightarrow \infty} Risk(\hat{f}_n) = Risk(f^*)$$

- How to adapt this notion in the case of PINNs?

Overfitting

- Study of limitations of PINNs
- To this end, we introduce a particular risk function.

$$\mathcal{R}_n(f) = \frac{1}{n} \sum_{i=1}^n \|f(x_i) - y_i\|_2^2 + \frac{\eta_n}{|\Omega|} \int_{\Omega} \|\mathcal{D}(f, x)\|^2 dx + \eta_e \mathbb{E} \left[\|f(x^{(e)}) - h(x^{(e)})\|_2^2 \right]$$

↑
expectation w.r.t. μ_E .

Regime where

$\left\{ \begin{array}{l} n \text{ is fixed (costly physical measurements)} \\ n_e, n_r \rightarrow +\infty \end{array} \right.$
 $(x_j^{(e)}, x_j^{(r)})$ can be freely sampled
up to computational resource

$$\begin{aligned} \mathcal{R}_{n, n_e, n_r}(f) = & \frac{1}{n} \sum_{i=1}^n \|f(x_i) - y_i\|_2^2 \\ & + \frac{\eta_n}{n_r} \sum_{i=1}^{n_r} \|\mathcal{D}(f, x_i^{(r)})\|_2^2 \\ & + \frac{\eta_e}{n_e} \sum_{i=1}^{n_e} \|f(x_i^{(e)}) - h(x_i^{(e)})\|_2^2 \end{aligned}$$

- Consider $\hat{\Theta}(p, n_e, n_r, \mathcal{D})$ a minimizing sequence of $\mathcal{R}_{n, n_e, n_r}$

$$\lim_{p \rightarrow +\infty} \mathcal{R}_{n, n_e, n_r}(\hat{f}_{\hat{\Theta}(p, n_e, n_r, \mathcal{D})}) = \inf_{\Theta \in \Theta_{H, \mathcal{D}}} \mathcal{R}_{n, n_e, n_r}(f_{\Theta})$$



- Focus on ERN-type estimators (no implicit bias here)

Definition: physical risk consistency

$$\lim_{n_e, n_r \rightarrow +\infty} \lim_{p \rightarrow +\infty} \mathcal{R}_n(\hat{f}_{\hat{\Theta}(p, n_e, n_r, \mathcal{D})}) = \inf_{f \in \text{NN}_{H, \mathcal{D}}(D)} \mathcal{R}_n(f)$$

We will show that PINNs can dramatically fail to be risk-consistent.

- Hybrid modelling with friction

$$\Omega =]0, T[$$

$$\forall f \in \mathcal{C}^2(\bar{\Omega}, \mathbb{R})$$

$$\mathcal{D}(u, x) = m u''(x) + \eta u'(x)$$

Dynamics of an object of mass m subjected to a fluid free of friction coefficient $\eta > 0$.

In this case, the empirical risk reads as

$$R_{n,n_r}(f_\theta) = \frac{1}{n} \sum_{i=1}^n |f_\theta(x_i) - y_i|^2 + \frac{\eta}{n_r} \sum_{l=1}^{n_r} \left(m f_\theta''(x_l^{(r)}) + \eta f_\theta'(x_l^{(r)}) \right)^2$$

prop: provided that $\exists y_i \neq y_j$, whenever $D \geq n-1$, for any n_r , for all $(x_l^{(r)})_{l=1, \dots, n_r}$, there exists a minimizing sequence $(\hat{f}_{\theta(p,n,n_r,D)})$ such that

$$\begin{cases} \lim_{p \rightarrow +\infty} R_{n,n_r}(\hat{f}_{\theta(p,n,n_r,D)}) = 0 & \text{(interpolation)} \\ \lim_{p \rightarrow +\infty} \mathcal{R}_n(\hat{f}_{\theta(p,n,n_r,D)}) = +\infty & \text{(PDE term exploding)} \end{cases}$$

The PINN estimator is not (physical) risk consistent.

this phenomenon is explained by the existence of piecewise constant functions interpolating the observations $x_1, \dots, x_n$ whose derivatives are

null at the points $X_1^{(a)}, \dots, X_{n_r}^{(a)}$ but diverge between these points.

Proof: Consider the following NN

$$f_{\hat{\Theta}_{(p,n,n_r,D)}}(x) = Y_{(1)} + \sum_{i=1}^n \frac{Y_{(i+1)} - Y_{(i)}}{2} \left[\tanh_p^{\text{OH}} \left(x - X_{(i)} - \frac{\delta(n,n_r)}{2} \right) + 1 \right]$$

where the observations $(X_1, Y_1) \dots (X_n, Y_n)$ are reordered into $(X_{(1)}, Y_{(1)}) \dots (X_{(n)}, Y_{(n)})$ such that $X_{(1)} \leq X_{(2)} \leq X_{(3)} \leq \dots \leq X_{(n)}$

$\delta(n, n_r)$ is the minimal distance between 2 distinct points in the input observations (X_i, Y_i) and the collocation points $(X_{\ell}^{(r)})_{\ell}$

$$\tanh_p(\cdot) = \tanh(p \cdot)$$

$\tanh_p^{\text{OH}}$ composition of $\tanh_p$ H times

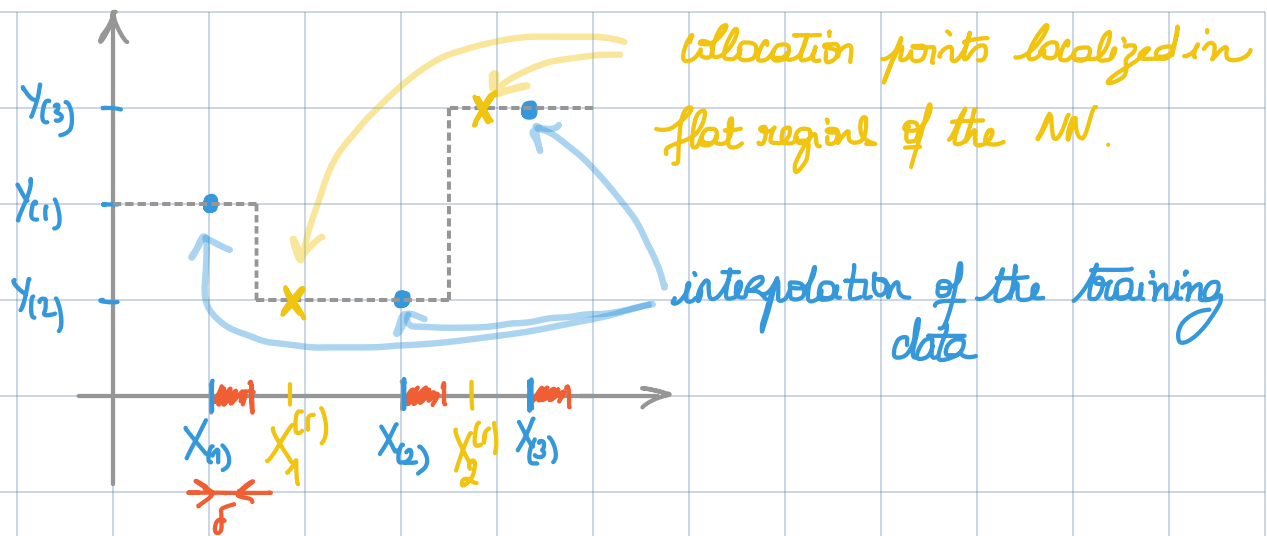
This NN has the following properties

(1) Interpolation of the training points

$$\lim_{p \rightarrow +\infty} f_{\hat{\Theta}_{(p,n,n_r,D)}}(X_i) = Y_i$$

Indeed for $\delta > 0$ $\lim \| \tanh_p^{\text{OH}} - \text{sgn} \|_{C^k(\mathbb{R} \setminus [-\delta, \delta])} = 0$

Therefore $\frac{1}{2} \left[\tanh_p^{\text{OH}} \left(x - X_{(i)} - \frac{\delta(n,n_r)}{2} \right) + 1 \right] \xrightarrow{p \rightarrow +\infty} \text{Heaviside of } x \text{ centered at } \left(X_{(i)} + \frac{\delta}{2} \right)$



② All derivatives higher than order 1 vanish almost everywhere.

$$\mathcal{D}(f_{\hat{\theta}_p}, x_e^{(r)}) = \left(m \underbrace{f_{\hat{\theta}_p}''(x_e^{(r)})}_{=0} + \eta \underbrace{f_{\hat{\theta}_p}'(x_e^{(r)})}_{=0} \right)^2 = 0 \quad \forall x_e^{(r)}.$$

③ But explode locally.

For any $0 < \varepsilon < \delta \ln(n)/4$,

$$\begin{aligned} \mathcal{R}_n(f_{\hat{\theta}(p, n, D)}) &\geq \frac{1}{T} \int_{[0, T]} \mathcal{D}(f_{\hat{\theta}(p, n, D)}, x)^2 dx \\ &\geq \frac{1}{T} \sum_{i=1}^{\tilde{n}} \int_{x_{(i)} + \delta/2 - \varepsilon}^{x_{(i)} + \delta/2 + \varepsilon} \mathcal{D}(f_{\hat{\theta}(p, n, D)}, x)^2 dx. \end{aligned}$$

Put the square outside the integral + fundamental theorem of integration.

$$\begin{aligned} &\geq \frac{1}{T} \sum_{i=1}^{\tilde{n}} \frac{1}{2\varepsilon} \left[\underbrace{m \left(\underbrace{f_{\hat{\theta}}'(x_{(i)} + \delta/2 + \varepsilon)}_{\downarrow \uparrow \rightarrow +\infty} - \underbrace{f_{\hat{\theta}}'(x_{(i)} + \delta/2 - \varepsilon)}_{\downarrow \uparrow \rightarrow +\infty} \right)}_{\downarrow \uparrow \rightarrow +\infty} + \eta \left(\underbrace{f_{\hat{\theta}}(x_{(i)} + \delta/2 + \varepsilon)}_{\downarrow \uparrow \rightarrow +\infty} - \underbrace{f_{\hat{\theta}}(x_{(i)} + \delta/2 - \varepsilon)}_{\downarrow \uparrow \rightarrow +\infty} \right) \right]^2 \\ &\geq \eta^2 \cdot \frac{1}{2\varepsilon T} \sum_{i=1}^{\tilde{n}} (y_{(i+1)} - y_{(i)})^2. \end{aligned}$$

Finally, $\lim_{p \rightarrow +\infty} \mathcal{R}_n(f_{\hat{\theta}(p, n, D)}) = +\infty$

□

Remarks:

- ① this pathological sequence of NN is such that $\|\Theta\|_2 \rightarrow +\infty$.
- ② the proof does not depend on the geometry of the collocation points $(X_e^{(r)})_e$ or the condition points $(X_e^{(c)})_e$ (holds with grids or quasi-Monte Carlo methods)
- ③ holds for any PDE with derivatives ≥ 1 involved.

• Similar behaviour in the case of PDE solver

Consider

$$\Omega =]-1; 1[\times]0; T[$$

$$\mathcal{D}(f, x) = \partial_t f - \partial_{xx}^2 f \quad \text{heat equation}$$

$$\text{Boundary conditions} \quad f(-1, t) = f(1, t) = 0$$

$$\text{Initial condition} \quad f(x, 0) = \tanh^{OH}(x + 0.5) - \tanh^{OH}(x - 0.5) + \tanh^{OH}(0.5) - \tanh^{OH}(1.5)$$

Bell function

Empirical risk function

$$R_{n_r, n_c}(f) = \frac{\lambda_c}{n_c} \sum_{j=1}^{n_c} |f(x_j^{(c)}) - h(x_j^{(c)})|^2 + \frac{1}{n_r} \sum_{e=1}^n \mathcal{D}(f, X_e^{(r)})^2$$

~~Physical~~ theoretical risk function

$$\mathcal{R}(f) = \lambda_c \mathbb{E} \left[|f(X^{(c)}) - h(X^{(c)})|^2 \right] + \frac{1}{|\Omega|} \int_{\Omega} \mathcal{D}(f, x)^2 dx$$

Prop: When $D \geq 4$, $\forall (n_e, n_r) \quad \forall (x_1^{(r)}, \dots, x_n^{(r)}) \quad \forall (x_1^{(e)}, \dots, x_{n_e}^{(e)})$

$\exists$ a minimizing sequence $(f_{\hat{\theta}(p, n_e, n_r, D)})_p$ s.t

$$\lim_{p \rightarrow +\infty} R_{n_e, n_r}(f_{\hat{\theta}(p, n_e, n_r, D)}) = 0$$

$$\lim_{p \rightarrow +\infty} R(f_{\hat{\theta}(p, n_e, n_r, D)}) = +\infty$$

This PINN estimator is not physical risk constant.

G Similarly, this estimator corresponds to a function that equals zero on Ω (and thus satisfies the linear PDE) while satisfying the initial condition on $\partial\Omega$

G Again this corresponds to a limit of neural networks f_θ such that $\|\theta\|_2 \rightarrow +\infty$.

Fighting overfitting

- Connection between L^2 norm of the weights and the NN regularity.

Prop: the following holds: $\forall \theta \in \mathcal{H}_{H,D}$

$$\|f_\theta\|_{C^k(\mathbb{R}^{d_{in}})} \leq C_{K,H} (D+1)^{HK+1} (1 + \|\theta\|_2)^{HK} \|\theta\|_2.$$

Remark: this bound is tight in the sense that there exists a sequence $(\theta_p) \in \mathcal{H}_{H,D}$ such that

$$(i) \quad \lim_{p \rightarrow \infty} \|\theta_p\|_2 = +\infty$$

$$(ii) \quad \|f_{\theta_p}\|_{C^k(\mathbb{R}^{d_{in}})} \geq \bar{C}_{K,H} \|\theta_p\|_2^{HK+1}.$$

- Idea: use a ridge-type / Eikonal-type regularization to avoid pathological minimizing sequences.

Def: Ridge risk function

$$R_{n,n_r,n_c}^{(ridge)}(f_\theta) = R_{n,n_r,n_c}(f_\theta) + \lambda_{(ridge)} \|\theta\|_2^2$$

hyperparameter

Denote $(\hat{\theta}_{(n,n_r,n_c,D)}^{(ridge)})_p$ a minimizing sequence of the ridge risk function

$$\lim_{p \rightarrow \infty} R_{n,n_r,n_c}^{(ridge)}(f_{\hat{\theta}_{(n,n_r,n_c,D)}^{(ridge)}}) = \inf_{\substack{\theta \in \mathcal{H}_{H,D}}} R_{n,n_r,n_c}^{(ridge)}.$$

• Note that ridge regularization is implementable in most deep learning libraries (e.g. keras, pytorch, ...), implemented via "weight decay".

• Class of polynomial operators

↖ bounded Lipschitz domain of $\mathbb{R}^3$

ex: Navier-Stokes equation on $\Omega = \Omega_1 \times]0, T[$, $f = (f_x, f_y, f_z, p)$
 (3rd eqt) $\mathcal{D}(f, x) = \alpha f_z - \frac{1}{3} \partial_z f_z - \eta \partial_{zz}^2 f_z + p' \partial_z p + g(x)$.
 It can be seen as a polynomial P of $f_z, \partial_z f_z, \partial_{zz}^2 f_z, \partial_z p$
 where P is given by $P(z_1, z_2, z_3, z_4, z_5) = z_3 - z_1 z_2 - \eta z_4 + p' z_5 + g$.

$\deg P = 2$ but $\deg \mathcal{D} = 3$ (counting the degree of the polynomial combined with the order of differentiation).

Encompass linear + nonlinear PDEs.

Theorem: ($H \geq 2$) Assume the condition fct h is Lipschitz and that

$\mathcal{D}$ is a polynomial operator.

By choosing $\tau_{\text{ridge}} = \frac{1}{(\min(r_n, r_r))^K}$ with $K = \frac{1}{12 + 4H(1 + 2H \deg \mathcal{D})}$

$$\lim_{r_n, r_r \rightarrow +\infty} \lim_{p \rightarrow +\infty} \mathcal{R}_n \left(\frac{f_p^{\tau_{\text{ridge}}}}{p} \right) = \inf_{NN_H(\mathcal{D})} \mathcal{R}_n$$

- The choice of the hyperparameter λ_{ridge} which vanishes when $n_e, n_r \rightarrow +\infty$ makes the ridge bias vanish.
- This choice depends on known quantities (NN depth, degree of the differential operator, nb of discretization points).
- Extension of this result to remove any approximation bias introduced by the class $NN_H(D)$:

$$\lim_{D \rightarrow +\infty} \lim_{n_e, n_r \rightarrow +\infty} \lim_{\lambda \rightarrow +\infty} \mathcal{R}_n \left(f_{\theta_{(p, n_e, n_r, D)}^{(\text{ridge})}} \right) = \inf_{\mathcal{C}^\infty(\bar{\Omega}, \mathbb{R}^{\text{out}})} \mathcal{R}_n$$

One can make D depend on n_e, n_r as well

$$(D = \min(n_e, n_r))^{\mathfrak{Z}} \text{ with } \mathfrak{Z} \text{ function of } H \text{ and } \deg \mathcal{D}.$$

In such a case

$$\lim_{n_e, n_r \rightarrow +\infty} \lim_{\lambda \rightarrow +\infty} \mathcal{R}_n \left(f_{\theta_{(p, n_e, n_r, D(n_e, n_r))}^{(\text{ridge})}} \right) = \inf_{\mathcal{C}^\infty(\bar{\Omega}, \mathbb{R}^{\text{out}})} \mathcal{R}_n$$

Proof: In the case of the 1D heat equation only
 $\partial_t f - \partial_{xx}^2 f = 0$ meaning that $\mathcal{D}(f, \cdot) = \partial_t f - \partial_{xx}^2 f$

① let $f_0 = 0 \in NN_H(D)$ the NN with parameters all 0.
 trivially $R_{n, n_e, n_r}^{(\text{ridge})}(f_0) = R_{n, n_e, n_r}(f_0)$

therefore,

$$R_{n,n_e,n_r}(f_0) = \frac{1}{n} \sum_{i=1}^n (f_0(x_i) - y_i)^2 + \frac{\lambda_n}{n_r} \sum_{i=1}^n [\mathcal{D}(f_0 x_i^{(n)})]^2$$

$$\leq \frac{1}{n} \sum_{i=1}^n |y_i|^2 + \lambda_n \cdot 2 =: UB$$

does not depend on n_r (ne if any) and λ_{ridge}

↑ 2 "coefficients" in the polynomial operator of sup norm 1.

$$\mathcal{D}(f, \cdot) = \underbrace{\phi_1}_{\uparrow} \partial_x f - \underbrace{\phi_2}_{\uparrow} \partial_{xx}^2 f$$

$$\|\phi_1\|_{\infty, \bar{\Sigma}} = \|\phi_2\|_{\infty, \bar{\Sigma}} = 1.$$

② let $\hat{\theta}_{p,n_e,n_r,D}^{(ridge)}$ be any minimizing

sequence of the empirical ridge risk: $\lim_{p \rightarrow \infty} R_{n,n_e,n_r}^{(ridge)}(f_{\hat{\theta}_{p,n_e,n_r,D}^{(ridge)}}) = \inf_{\theta \in \mathcal{H}_{H,D}} R_{n,n_e,n_r}(f_\theta)$

call $m_{r,e} = \min(n_e, n_r)$

Define $E_1^{large}(m_{r,e}) = \{\theta \in \mathcal{H}_{H,D}, \|\theta\|_2 \geq m_{r,e}^K\}$

$E_2^{inter}(m_{r,e}) = \{\theta \in \mathcal{H}_{H,D}, m_{r,e}^{K/4} \leq \|\theta\|_2 \leq m_{r,e}^K\}$

$E_3^{small}(m_{r,e}) = \{\theta \in \mathcal{H}_{H,D}, \|\theta\|_2 \leq m_{r,e}^{K/4}\}$

Remark that $\mathcal{H}_{H,D} = E_1^{large} \cup E_2^{inter} \cup E_3^{small}$.

Summary of what's next:

$\theta_{small} \equiv$ no problem.

in-between $\equiv$ be careful.

$\theta_{large} \equiv$ does not happen

Idea of the proof: show that almost surely, given any m_r and n_r , for r large enough, $\hat{\theta}_{(p, n_r, D)}^{(\text{ridge})} \in E_2^{\text{inter}} \cup E_3^{\text{small}}$.
 Moreover on $E_2^{\text{inter}} \cup E_3^{\text{small}}$, the empirical risk function $R_{n, n_r}^{(\text{ridge})}$ is close to the theoretical risk R_n .

③ @ $\forall \theta \in E_1^{\text{large}}$ $R_{n, n_r}^{(\text{ridge})}(\theta) \geq \lambda_{\text{ridge}} \|\theta\|_2^2 \geq m_{n, r}^K$.

Once $m_{n, r} \geq (UB+1)^{1/K}$,

$$\begin{aligned} \inf_{\theta \in E_3^{\text{small}}} R_{n, n_r}^{(\text{ridge})}(f_\theta) + 1 &\leq R_{n, n_r}^{(\text{ridge})}(f_\theta) + 1 \\ &\leq UB + 1 \\ &\leq m_{n, r}^K \\ &\leq \inf_{\theta \in E_1^{\text{large}}} R_{n, n_r}^{(\text{ridge})}(f_\theta) \end{aligned}$$

This shows that for n_r large enough, $\hat{\theta}_{(p, n_r, D)}^{(\text{ridge})} \notin E_1^{\text{large}}$.

(b) We can show that

(*) $\sup_{\theta \in E_2^{\text{inter}} \cup E_3^{\text{small}}} \left| \frac{1}{n_r} \sum_{l=1}^{n_r} \mathfrak{D}(f_\theta, X_l^{(r)})^2 - \frac{1}{|S|} \int_S \mathfrak{D}(f_\theta, z)^2 dz \right| \leq \log^2(n_r) n_r^{\beta-1/2}$

with $\beta = (2 + H(1 + (2 + H) \deg \mathfrak{D}))$.

(Admitted).

Uniform control of stochastic processes (Hoeffding / Dudley / McDiarmid)

Thus almost surely for all n_r large enough and $\theta \in E_2(n_r)$

$$R_{n,n_r}^{(\text{ridge})}(f_\theta) \geq R_n(f_\theta) + \lambda_{(\text{ridge})} \|\theta\|_2^2 - \cancel{2} \log^2(n_r) n_r^{\beta-1/2}$$

~~coming from the absolute value.~~

≥ 0 ?

Yes! Because

for all $\theta \in E_2^{\text{inter}}$,

$$\lambda_{(\text{ridge})} \|\theta\|_2^2 \geq n_r^{-K/2}$$

n_r^{-K} " $\stackrel{\text{ridge}}{\geq} n_r^{K/4}$

and $-K/2 \geq \beta - 1/2$

then almost surely for n_r large enough and for all $\theta \in E_2^{\text{inter}}(n_r)$

$$R_{n,n_r}^{(\text{ridge})}(f_\theta) \geq R_n(f_\theta)$$

there, on E_2^{inter} , the empirical risk controls the theoretical one

② $\forall \theta \in E_3^{\text{small}} \quad \lambda_{(\text{ridge})} \|\theta\|_2^2 \leq n_r^{-K/2}$

Using $\textcircled{*}$, we deduce that for all n_r large enough for all $\theta \in E_3^{\text{small}}$

$$|R_{n,n_r}^{(\text{ridge})}(f_\theta) - R_n(f_\theta)| \leq 2 \log^2(n_r) n_r^{-K/2}$$

one coming from integral approx.
one coming from the ridge reg.

(d) Fix $\varepsilon > 0$

Call $(\theta_p)_p$ any minimizing sequence of the theoretical risk R_n

$$\lim_{p \rightarrow \infty} R_n(f_{\theta_p}) = \inf_{\theta \in \mathcal{H}_{n,D}} R_n(f_\theta)$$

By defⁿ $\exists p_\varepsilon$ such that $|R_n(f_{\theta_{p_\varepsilon}}) - \inf_{\theta \in \mathcal{H}_{n,D}} R_n(f_\theta)| \leq \varepsilon$.

→ For fixed n_r , according to (a), for p large enough

$$\hat{\theta}_{p, n_r, D}^{(\text{ridge})} \in E_2(n_r) \cup E_3(n_r).$$

→ According to (b) & (c)

$$R_n(f_{\hat{\theta}_{p, n_r, D}^{(\text{ridge})}}) \leq R_{n, n_r}^{(\text{ridge})}(f_{\hat{\theta}_{p, n_r, D}^{(\text{ridge})}}) + 2 \log^2(n_r) n_r^{-K/2}$$

→ By defⁿ of the minimizing sequence $\hat{\theta}_{p, n_r, D}^{(\text{ridge})}$, for p large enough,

$$R_{n, n_r}^{(\text{ridge})}(f_{\hat{\theta}_{p, n_r, D}^{(\text{ridge})}}) \leq \inf_{\theta \in \mathcal{H}_{n_r, D}} R_{n, n_r}^{(\text{ridge})} + \varepsilon$$

→ According to (c)

$$\begin{aligned} \inf_{\theta \in E_2(n_r) \cup E_3(n_r)} R_{n, n_r}^{(\text{ridge})}(f_\theta) &\leq \inf_{\theta \in E_3(n_r)} R_{n, n_r}^{(\text{ridge})}(f_\theta) \\ &\leq \inf_{\theta \in E_3(n_r)} R_n(f_\theta) + \underline{2 \log^2(n_r) n_r^{-K/2}} \end{aligned}$$

$\rightarrow$ For all n large enough $\Theta_p \in E_3^{small}(n)$
 therefore $\inf_{\Theta \in E_3^{small}(n)} R_n(f_\Theta) \leq R_n(f_{\Theta_p})$

Combining all, almost surely for n and p large enough
 $R_n(\hat{f}_{\Theta_{p,n,r,D}}^{(ridge)}) \leq \inf_{\Theta \in \mathcal{H}_{n,D}} R_n(f_\Theta) + 3\varepsilon$

As ε is arbitrary, we get $\lim_{n \rightarrow \infty} \lim_{p \rightarrow \infty} R_n(\hat{f}_{\Theta_{p,n,r,D}}^{(ridge)}) = \inf_{\Theta \in \mathcal{H}_{n,D}} R_n(f_\Theta)$



Open question :

- Implicit regularization in PINN training.
- Spectral bias.

Strong convergence of PINNs for linear PDE

- Good CV properties in terms of risk $\mathcal{R}_n$ do not imply good CV properties in terms of function, for instance

$$\hat{f}_{\text{PINN}} \xrightarrow{?} f^* \text{ in } L^2\text{-sense}(?)$$

- A first example in hybrid modeling setting

$$\text{dim} = 2 \quad \text{dout} = 1$$

$$\Omega =]0,1[\times]0,T[$$

$$\partial_t f + \partial_x f = 0$$

(advection equation)

$$h(x,0) = 1 \quad \forall x$$

(initial condition)

$$h(0,t) = 1 \quad \forall t$$

(boundary condition)

Prior: the regression function f^* should be close to 1.

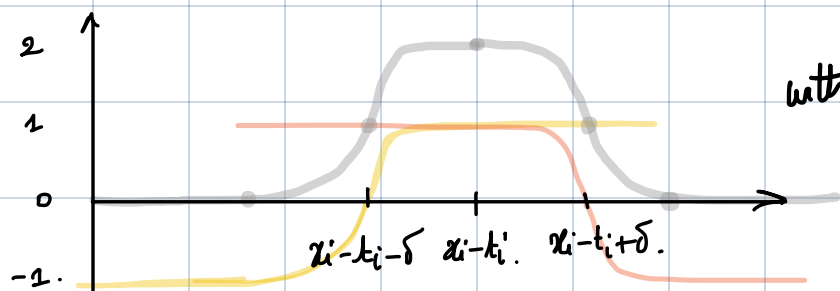
Consider the sequence of NN:

$$\text{sgn}(x-t-x_i+t_i+\delta)$$

$$f_{\delta,p}(x,t) = 1 + \frac{\sum_{i=1}^p (y_i - 1)}{2} \left(\tanh_p^{\text{OH}}(x-t-x_i+t_i+\delta) - \tanh_p^{\text{OH}}(x-t-x_i+t_i-\delta) \right)$$

$$x_i = (x_i, t_i)$$

$$\hookrightarrow \text{sgn}(x-t-x_i+t_i-\delta)$$



$$\text{with } \delta \leq \frac{1}{2} \min_{i \neq j} |x_i - x_j + t_i - t_j|$$

Indeed, note that by the step shape, we get

$$|f(x+\delta) - f(x)| = 1 = \left| \int_x^{x+\delta} f'(u) du \right| = \left| \langle f', \mathbb{1}_{[x, x+\delta]} \rangle_{L^2} \right|$$

$$\leq \sqrt{\int_x^{x+\delta} (f')^2(u) du} \sqrt{\delta}.$$

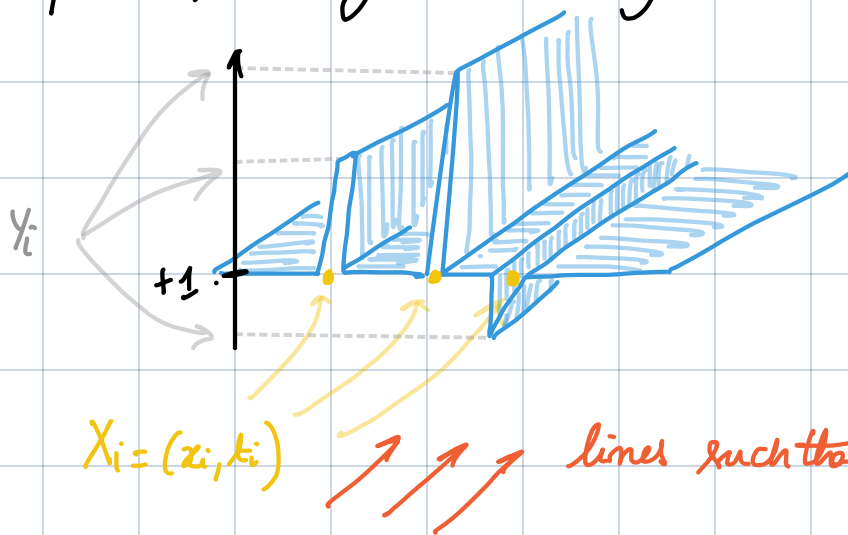
by Cauchy-Schwarz

therefore $\|f'\|_{L^2(\Omega)} \geq 1/\sqrt{\delta}.$

□

$$\oplus \quad f_{\delta,p}(x_i, t_i) \xrightarrow{p \rightarrow +\infty} y_i$$

$\oplus \quad f_{\delta,p}$ satisfies the equation, as being constant along the lines $x+t = cte$.



therefore $\lim_{p \rightarrow +\infty} \mathcal{R}(f_{\delta,p}) = 0$ by $\oplus$ and $\oplus$.

$$\text{If } D \geq 2n, \quad \inf_{f \in \text{NNH}(D)} \mathcal{R}_n(f) = 0 \Rightarrow f_{\hat{\theta}(\text{bridge})} \xrightarrow[p \rightarrow +\infty]{L^2(\Omega)} \mathbb{1}_{\Omega}$$

✓ Fine if the model is accurate independently of n and f^* !!!

✗ problematic if the model is not exact.

• A second example in PDE solve

$$\Omega =]-1; 1[$$

$$\left\{ \begin{array}{l} h(1) = 1 \\ \mathcal{D}(f, x) = x f'(x) \end{array} \right.$$

Clearly $f^*(x) = 1$ is the only strong solⁿ of the PDE

Consider the NN sequence to be $f_p = \tanh_p \circ \tanh^{(H-1)}$

$$\lim_{p \rightarrow \infty} \mathcal{R}(\hat{f}_p) = \mathcal{R}(f^*) = 0 \quad (\text{as } \hat{f}_p \text{ satisfies the ODE and } \hat{f}_p(1) = 1)$$

$(\hat{f}_p)_p$ is a minimizing sequence of $\mathcal{R}$.

But $\hat{f}_\infty(x) = \text{sgn}(x) \neq f^*$.

• To retrieve strong convergence properties, one can use Sobolev regularization

• Assumption [linear PDEs]

Assume that $\mathcal{D}$ is an affine operator (of order K) of f and its derivatives

$$\mathcal{D}(f, x) = \mathcal{D}^{(\text{lin})}(f, x) + B(x)$$

of order K .

$$\sum_{|\alpha| \leq K} \langle A_\alpha(x), \partial^\alpha f(x) \rangle$$

$\prod_{\alpha \in \mathcal{A}} (\Omega, \mathbb{R}^{\text{data}})$

for the sake of presentation.

in the paper, we can handle a 2nd member.

ex: advection, heat, wave, Maxwell equations.

- Regularized theoretical risk

$$\mathcal{R}_n^{(\text{reg})}(f) = \mathcal{R}_n(f) + \lambda_{(\text{ss})} \|f\|_{\mathcal{H}^{m+1}(\Omega)}^2$$

with $\|f\|_{\mathcal{H}^{m+1}(\Omega)}^2 = \sum_{|\alpha| \leq m+1} \|\partial^\alpha f\|_{L^2(\Omega)}^2$.

- Regularized empirical risk

$$\mathcal{R}_{n,n_e,n_r}^{(\text{reg})}(f) = \mathcal{R}_{n,n_e,n_r}(f) + \lambda_{(\text{ridge})} \|\theta\|_2^2 + \frac{\lambda_{(\text{ss})}}{n_e} \sum_{\ell=1}^{n_e} \sum_{|\alpha| \leq m+1} \|\partial^\alpha f(x_\ell^{(e)})\|_2^2$$

✓ Can be straightforwardly implemented in the usual PINN framework by considering the Sobolev penalty as additional PDE.

In what follows, for the sake of presentation, we discard the boundary condition (cf. gray parts).

Proposition [Characterization of the unique minimizer of $\mathcal{R}_n^{(reg)}$]

Assume $\mathcal{D}$ to be of order K and to encode a linear PDE.

$$m \geq \max \left(\left\lfloor \frac{d_{in}}{2} \right\rfloor, K \right)$$

then, $\mathcal{R}_n^{(reg)}$ has a unique minimizer $\hat{f}_n$ over $H^{m+1}(\Omega)$, characterized to be the unique element of $H^{m+1}(\Omega)$ such that

$$\forall v \in H^{m+1}(\Omega) \quad \mathcal{A}_n(\hat{f}_n, v) = \mathcal{B}_n(v)$$

with

$$\begin{aligned} \mathcal{A}_n(\hat{f}_n, v) = & \frac{1}{n} \sum_{i=1}^n \langle \Pi(\hat{f}_n)(x_i), \Pi(v)(x_i) \rangle \\ & + \lambda_2 \mathbb{E} \langle \Pi(\hat{f}_n)(x^e), \Pi(v)(x^e) \rangle \\ & + \frac{\lambda_2}{|\Omega|} \int_{\Omega} \mathcal{D}^{(lin)}(\hat{f}_n, x) \mathcal{D}^{(lin)}(v, x) dx \\ & + \frac{\lambda_{(2)}}{|\Omega|} \sum_{|k| \leq m+1} \int_{\Omega} \langle \partial^k \hat{f}_n(x), \partial^k v(x) \rangle dx \end{aligned}$$

$$\begin{aligned} \mathcal{B}_n(v) = & \frac{1}{n} \sum_{i=1}^n \langle y_i, \Pi(v)(x_i) \rangle + \\ & + \lambda_2 \mathbb{E} \left[\langle \Pi(v)(x^e), h(x^e) \rangle \right] \\ & - \frac{\lambda_2}{|\Omega|} \int_{\Omega} B(x) \mathcal{D}^{(lin)}(v, x) dx. \end{aligned}$$

$$\Pi: H^{m+1}(\Omega, \mathbb{R}^{d_{out}}) \rightarrow C^0(\Omega, \mathbb{R}^{d_{out}})$$

Π -called Sobolev embedding

such that $\Pi(f)$ is the unique continuous f that coincides with f almost everywhere.

Weak
formulation
of PDE on
 $H^m(\Omega, \mathbb{R}^{d_{out}})$

↳ Lax-Milgram based result.

↳ Remark that

$$\mathcal{R}_n^{(reg)}(f) = \mathcal{A}_n(f, f) - 2\mathcal{B}_n(f) + \frac{1}{n} \sum_{i=1}^n \|Y_i\|^2 + \mu \mathbb{E} \|h(X^{(a)})\|_2^2 + \frac{1}{|\Omega|} \int_{\Omega} B^2(x) dx.$$

Proof: For the sake of simplicity, in the

proof, we discard the boundary conditions & 2nd member in the PDE

Remark that

$$\textcircled{1} \quad \mathcal{A}_n(f, f) - 2\mathcal{B}_n(f) = \mathcal{R}_n^{(reg)}(f) - \frac{1}{n} \sum_{i=1}^n \|Y_i\|^2$$

$$\textcircled{2} \quad \mathcal{A}_n(f, f) \geq \lambda_{(sub)} \|f\|_{H^{m+1}(\Omega)}^2$$

meaning that $\mathcal{A}_n$ is coercive on the normed space $H^{m+1}(\Omega, \|\cdot\|_{H^{m+1}(\Omega)})$

Since $m+1 > \max(d/2, K)$, one has

$$|\mathcal{A}_n(f, g)| \leq \left[C_{\Omega}^2 + \left(\sum_{|K| \leq K} \|A_{K, \alpha}\|_{\infty, \Omega} \right)^2 + \lambda_{sub} \right] \|f\|_{H^{m+1}(\Omega)}^2 \|g\|_{H^{m+1}(\Omega)}^2$$

and

$$|\mathcal{B}_n(f)| \leq C_{\Omega} \frac{1}{n} \sum_{i=1}^n \|Y_i\|_2 \|f\|_{H^{m+1}(\Omega)}^2$$

therefore, $\mathcal{A}_n$ and $\mathcal{B}_n$ are continuous

By Lax-Milgram theorem [Brezis, 2010, Corollary 5.8]

$\exists! \hat{f} \in H^{m+1}(\Omega, \mathbb{R}^{d_{out}})$ such that

$$\mathcal{A}_n(\hat{f}, \hat{f}) - 2\mathcal{B}_n(\hat{f}) = \min_{f \in H^{m+1}(\Omega)} \mathcal{A}_n(f, f) - 2\mathcal{B}_n(f)$$

$\hat{f}$ is the unique minimizer of $\mathcal{R}_n^{(reg)}$ over $H^{m+1}(\Omega, \mathbb{R}^{d_{out}})$
 Again Lax-Milgram then gives that $\hat{f}$ is the unique
 element of $H^{m+1}(\Omega)$ s.t. $\forall g \in H^{m+1}(\Omega) \quad \mathcal{A}_n(\hat{f}, g) = \mathcal{B}_n(g)$. $\square$

✓ The former proposition ensures that the Sobolev regularization makes the PINN problem well-posed, i.e., the theoretical risk function admits a unique minimizer.

? Next question: what about CV to this unique minimizer?

Proof [From regularized risk consistency to strong convergence]

Assume that $m \geq \max(\lfloor d_{in}/2 \rfloor, K)$

let $(f_p)_p \in C^\infty(\bar{\Omega}, \mathbb{R}^{d_{out}})$

such that $\lim_{p \rightarrow \infty} \mathcal{R}_n^{(reg)}(f_p) = \inf_{f \in C^\infty(\bar{\Omega}, \mathbb{R}^{d_{out}})} \mathcal{R}_n^{(reg)}(f)$

minimizing sequence of $\mathcal{R}_n^{(reg)}$

then $\mathcal{R}_n^{(reg)}$

$$\lim_{p \rightarrow \infty} \|f_p - \hat{f}_n\|_{H^{m+1}(\Omega)} = 0$$

unique minimizer of $\mathcal{R}_n^{(reg)}$ over $H^{m+1}(\Omega, \mathbb{R}^{d_{out}})$

proof: admitted

Message: minimizing seqs of $\mathcal{R}_n^{(reg)}$ converge to the unique minimizer of $H^{m+1}(\Omega)$

Thm: [Strong convergence of regularized PINNs]

Assume that

$\mathcal{D}$ is an affine operator

$$m \geq \max \left[\frac{\dim}{2}, \kappa \right]$$

the condition function h is Lipschitz

let $(\hat{\Theta}^{(reg)}(p, n_e, n_r, \mathcal{D}))_p$ be a min. sequence of the regularized empirical risk function

$$R_{n, n_e, n_r}^{(reg)}(f_\theta) = R_{n, n_e, n_r}(f_\theta) + \lambda_{(ridge)} \|\theta\|_2^2 + \frac{\lambda_{(stab)}}{n} \sum_{l=1}^n \sum_{|k| \leq m+1} \|\partial^k f_\theta(x_l^{(n)})\|_2^2$$

over the class of $NN_H(\mathcal{D})$.

then, choosing $\lambda_{(ridge)} = \min(n_e, n_r)^{-\kappa}$ with $\kappa = \frac{1}{12 + 4H(1 + (2+H)(m+2))}$ one has

$$\lim_{D \rightarrow \infty} \lim_{n_e, n_r \rightarrow \infty} \lim_{p \rightarrow \infty} \left\| \hat{f}_{p, n_e, n_r, \mathcal{D}}^{(reg)} - \hat{f}_n \right\|_{H^m(\Omega)} = 0.$$

unique minimizer of $R_n^{(reg)}$
over $H^{m+1}(\Omega, \mathbb{R}^{d_{out}})$

Message: minimizing seqs of the empirical regularized risk converge to the unique minimizer of the regularized theoretical risk

✓ the PINN $\hat{f}_p^{(reg)}$ converges to the unique minimizer $\hat{f}_n$ of the theoretical risk

? What can we say in terms of CV to f^* ?

then [Strong CV of linear PDE solves].

Same assumptions as before -

+ The PDE admits a unique solution f^* in $H^{m+1}(\Omega, \mathbb{R}^{d_{out}})$

then,

$$\lim_{\lambda \rightarrow 0} \lim_{D \rightarrow 0} \lim_{n, n_r \rightarrow \infty} \lim_{p \rightarrow 0} \left\| \hat{f}_{\hat{\theta}_{reg}^{(p, n, n_r, D, \lambda_{sub})}} - f^* \right\|_{H^m(\Omega)} = 0$$

For the hybrid modeling framework, we need to measure the gap between f^* and the physical prior.

Def: [physical inconsistency]

For any $f \in H^{m+1}(\Omega, \mathbb{R}^{d_{out}})$,

$$PI(f) = \frac{1}{2} \mathbb{E} \left\| \pi(f)(x^{(a)}) - h(x^{(a)}) \right\|^2 + \frac{\lambda_2}{|\Omega|} \int \mathcal{D}^2(u, x) dx$$

↳ PI measures the modeling error.

Better the model, lower $PI(\tilde{f}^*)$

↳ Remark that $\mathcal{R}_n(f) = \frac{1}{n} \sum_{i=1}^n \left\| \pi(f)(x_i) - y_i \right\|_2^2 + PI(f)$

Prop: Under the same assumptions as before. Assume that $f^{\text{po}} \in H^{m+1}(\Omega, \mathbb{R}^{\text{data}})$, let

Choose λ_{ridge} as before w.r.t n_r (and n_e) such that $\lambda_{\text{ridge}} \xrightarrow{n_e, n_r \rightarrow \infty} 0$.

$$\lambda_x = \frac{\log n}{\sqrt{n}} \quad \lambda_{\text{ob}} = \frac{1}{\sqrt{n}}$$

then

STATISTICAL ACCURACY.

$$\lim_{D \rightarrow \infty} \lim_{n_e, n_r \rightarrow \infty} \lim_{p \rightarrow 0} E \int_{\Omega} \|f_{\hat{\theta}^{(\text{reg})}(p, n_e, n_r, D)}^{(n)} - f^{\text{po}}\|_2^2 d\mu_X \lesssim \frac{\log^2(n)}{\sqrt{n}}$$

PHYSICAL CONSISTENCY.

$$\lim_{D \rightarrow \infty} \lim_{n_e, n_r \rightarrow \infty} \lim_{p \rightarrow 0} E \left[\text{PI} \left(f_{\hat{\theta}^{(\text{reg})}(p, n_e, n_r, D)}^{(n)} \right) \right] \leq \text{PI}(f^{\text{po}}) + o(1)_{n \rightarrow \infty}.$$

In the lecture: $\lambda_x = \lambda_e = \frac{\log n}{\sqrt{n}} \quad \lambda_{\text{ob}} = \frac{1}{\sqrt{n}} \quad \lambda_{\text{data}} = 1$

Choice of λ_{ridge} unaffected by the rescaling since we take the asymptotic in n_e, n_r first.

* Choice in the article $\lambda_x = 1 \quad \lambda_e = 1 \quad \lambda_{\text{ob}} = 1/\log n \quad \lambda_{\text{data}} = \sqrt{n}/\log n$